

# RHEL: Services basic management - systemd

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## RHEL: Services basic management - systemd

```
# Tested on CentOS 7

# systemd is the new Fedora init system adopted by Red Hat from RHEL
# 7 on.

# It is backwards compatible with SysV init scripts, enhances the
# administrative process
# and provides new features such as parallel startup of system
# services at boot time or
# dependency-based service control, for instance.

# systemd introduces the concept of systemd units. These units are
# represented by unit
# configuration files and encapsulate information about system
# services and other objects
# that are relevant to the init system.
#
# systemd unit locations:
#
# /usr/lib/systemd/system   Systemd units distributed with installed
# RPM packages.
#
# /run/systemd/system     Systemd units created at run time. This
# directory takes
# precedence over the directory with
# installed service units.
#
```

```
# /etc/systemd/system      Systemd units created and managed by the
system administrator.
#                          This directory takes precedence over the
directory with runtime
#                          units.
```

```
# "systemctl" command shows the state of all services. It queries the
state of services,
# both systemd native and SysV/LSB services. It shows for each
service, whether it managed
# to start up or failed (time-out, non-zero exit code, abnormal
termination):
```

### systemctl

UNIT	LOAD	ACTIVE	SUB
DESCRIPTION			
[...]			
auditd.service Security Auditing Service	loaded	active	running
chronyd.service client/server	loaded	active	running NTP
crond.service Command Scheduler	loaded	active	running
dbus.service System Message Bus	loaded	active	running D-Bus
getty@tty1.service on tty1	loaded	active	running Getty
<b>* kdump.service</b> <b>recovery kernel arming</b>	<b>loaded</b>	<b>failed</b>	<b>failed Crash</b>
kmod-static-nodes.service Create list of required static device nodes for the current kernel	loaded	active	exited
lvm2-monitor.service Monitoring of LVM2 mirrors, snapshots etc. using dmeventd or progress polling	loaded	active	exited
network.service Bring up/down networking	loaded	active	exited LSB:
[...]			

```

    local-fs-pre.target          loaded active active    Local
File Systems (Pre)
    local-fs.target             loaded active active    Local
File Systems
    multi-user.target           loaded active active    Multi-
User System
    network-online.target       loaded active active
Network is Online
    network.target              loaded active active
Network
    paths.target                loaded active active    Paths
    remote-fs.target            loaded active active
Remote File Systems
    slices.target               loaded active active
Slices
    sockets.target              loaded active active
Sockets
    swap.target                  loaded active active    Swap
    sysinit.target              loaded active active
System Initialization
    timers.target               loaded active active
Timers
    systemd-tmpfiles-clean.timer loaded active waiting    Daily
Cleanup of Temporary Directories

```

LOAD = Reflects whether the unit definition was properly loaded.

ACTIVE = The high-level unit activation state, i.e. generalization of SUB.

SUB = The low-level unit activation state, values depend on unit type.

109 loaded units listed. Pass --all to see loaded but inactive units, too.

To show all installed unit files use 'systemctl list-unit-files'.

# To have a quick view of system status, run "**systemctl status**":

## systemctl status

\* myserv

State: running

Jobs: 0 queued

Failed: 0 units

Since: Tue 2016-02-02 09:13:06 CET; 1h 11min ago

CGroup: /

```
| -1 /usr/lib/systemd/systemd --switched-root --system
--deserialize 21
|-user.slice
| |-user-0.slice
|   |-session-3.scope
|     |-2162 /usr/sbin/anacron -s
|     |-session-2.scope
|       |-2114 sshd: root@pts/1
|       |-2116 -bash
|       |-2212 man systemd-cgls
|       |-2221 less -s
|     |-session-1.scope
|       |-2068 sshd: root@pts/0
|       |-2070 -bash
|       |-2323 systemctl status
|       |-2324 less
|-system.slice
  |-mysqld.service
    |-1014 /usr/sbin/mysqld --daemonize --pid-
file=/var/run/mysqld/mysqld.pid
  |-tuned.service
    |-939 /usr/bin/python -Es /usr/sbin/tuned -l -P
[...]
```

|-system-getty.slice

|-getty@tty1.service

|-764 /sbin/agetty --noclear tty1 linux

# To have a little bit more information about a service, use

```
"systemctl status <service>".
```

```
# systemd tracks and remembers whether the service started up  
successfully or not  
# both during start-up and runtime.
```

```
# Example of a service that failed to stay up, when it ran as PID  
2148, and indicates that  
# the process failed with exit status of 1:
```

```
systemctl status kdump
```

```
* kdump.service - Crash recovery kernel arming
```

```
Loaded: loaded (/usr/lib/systemd/system/kdump.service; enabled;  
vendor preset: enabled)
```

```
Active: failed (Result: exit-code) since Mon 2016-01-25 14:11:55  
CET; 1h 50min ago
```

```
Main PID: 2148 (code=exited, status=1/FAILURE)
```

```
Jan 25 14:11:21 myserver systemd[1]: Starting Crash recovery kernel  
arming...
```

```
Jan 25 14:11:55 myserver kdumpctl[2148]: No memory reserved for crash  
kernel.
```

```
Jan 25 14:11:55 myserver kdumpctl[2148]: Starting kdump: [FAILED]
```

```
Jan 25 14:11:55 myserver systemd[1]: kdump.service: main process  
exited, code=exited, status=1/FAILURE
```

```
Jan 25 14:11:55 myserver systemd[1]: Failed to start Crash recovery  
kernel arming.
```

```
Jan 25 14:11:55 myserver systemd[1]: Unit kdump.service entered  
failed state.
```

```
Jan 25 14:11:55 myserver systemd[1]: kdump.service failed.
```

```
# Managing of system services with "systemctl"
```

```
# -----  
-----
```

```
# Start a service
```

```
systemctl start <service>

# Stop a service
systemctl stop <service>

# Restart a service
systemctl restart <service>

# Restart a service only if it is running
systemctl try-restart <service>

# Reload configuration
systemctl reload <service>

# Check if a service is running
systemctl status <service>
systemctl is-active <service>

# Display the status of all services
systemctl list-units --type service
systemctl list-units --all

# Enable a service
systemctl enable <service>

# Disable a service
systemctl disable <service>

# Check if a service is enabled
systemctl status <service>
systemctl is-enabled <service>

# List all services and check if they are enabled
systemctl list-unit-files --type service

# List services that are ordered to start before the specified unit
systemctl list-dependencies --after [<service>]
```

```
# List services that are ordered to start after the specified unit
systemctl list-dependencies --before [<service>]

# SYSTEMD TARGETS
# -----
-----

# In RHEL 7, the concept of runlevels has been replaced with systemd
"targets".

# Systemd targets are represented by target units. Target units end
with the .target file
# extension and their only purpose is to group together other systemd
units through a chain
# of dependencies.

# RHEL 7 has a number of predefined targets similar to the standard
set of runlevels from
# the previous releases.

# systemd Targets

runlevel0.target, poweroff.target      shut down and power off the
system
runlevel1.target, rescue.target        set up a rescue shell
runlevel2.target, multi-user.target    set up a non-graphical multi-
user system
runlevel3.target, multi-user.target    set up a non-graphical multi-
user system
runlevel4.target, multi-user.target    set up a non-graphical multi-
user system
runlevel5.target, graphical.target     set up a graphical multi-
user system
```

```
runlevel6.target, reboot.target          shut down and reboot the
system

# List currently loaded target units:
systemctl list-units --type target

# Change the current target:
systemctl isolate <name.target>

# Verify / modify the default target:
systemctl get-default
systemctl set-default <name.target>

# The last command will replace the
/etc/systemd/system/default.target file with a
# symbolic link to /usr/lib/systemd/system/<name.target>:

systemctl set-default graphical.target
    Removed symlink /etc/systemd/system/default.target.
    Created symlink from /etc/systemd/system/default.target to
/usr/lib/systemd/system/graphical.target.

# Switching to default/rescue/emergency mode

systemctl default          # Enter default mode. Equivalent to systemctl
isolate default.target

systemctl rescue           # or systemctl isolate rescue.target
systemctl --no-wall rescue # prevent sending informative
message to users
```



```
# In emergency mode, the system only mounts the root file system only
for reading and
# starts a few essential services. In RHEL 7, emergency mode requires
the root password.
```

```
systemctl emergency                # or systemctl isolate
emergency.target
systemctl --no-wall emergency      # prevent sending informative
message to users
```

```
# Halting, powering off and rebooting system
```

```
# In RHEL 7, systemctl replaces power management commands; these
commands are available in
# the system for compatibility reasons but it is recommended to use
systemctl when
# possible:
```

```
ll /usr/sbin/halt /usr/sbin/poweroff /usr/sbin/shutdown
/usr/sbin/reboot
  lrwxrwxrwx. 1 root root 16 Jan 15 18:33 /usr/sbin/halt ->
  ../bin/systemctl
  lrwxrwxrwx. 1 root root 16 Jan 15 18:33 /usr/sbin/poweroff ->
  ../bin/systemctl
  lrwxrwxrwx. 1 root root 16 Jan 15 18:33 /usr/sbin/reboot ->
  ../bin/systemctl
  lrwxrwxrwx. 1 root root 16 Jan 15 18:33 /usr/sbin/shutdown ->
  ../bin/systemctl
```

```
# Halt the system
```

```
systemctl halt
```

```
# Power off the system
```

```
systemctl poweroff
```

```
# Restart the system
```

```
systemctl reboot
```

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